

Digital Control Systems Analysis And Design Phillips

New edition of a text for senior undergraduate and first-year graduate level engineering students. Prerequisites are a course on introductory control systems, a course on ordinary differential equations, and familiarity with MATLAB computations (or MATLAB can be studied concurrently). Annotation copyright by Book News, Inc., Portland, OR

Digital Control Systems Analysis and Design is appropriate for a one semester/two-quarter senior-level course in digital or discrete-time controls. It is also a suitable reference for practicing engineers. This best-selling text places emphasis on the practical aspects of designing and implementing digital control systems. This program presents a better teaching and learning experience--for you and your students. Provide MATLAB programs to students: Short MATLAB programs have been included in many of the examples, which allow students to experiment and learn more skills. Motivate students with running applications that are featured throughout the book: Simple physical systems are introduced in one chapter and then used again later to illuminate more advanced material. Reinforce core concepts with examples and problems: Numerous problems and worked examples help students grasp the text's concepts. Keep your course current: A new chapter on system identification (Chapter 11) is included in this edition

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Digital controllers are part of nearly all modern personal, industrial, and transportation systems. Every senior or graduate student of electrical, chemical or mechanical engineering should therefore be familiar with the basic theory of digital controllers. This new text covers the fundamental principles and applications of digital control engineering, with emphasis on engineering design. Fadali and Visioli cover analysis and design of digitally controlled systems and describe applications of digital controls in a wide range of fields. With worked examples and Matlab applications in every chapter and many end-of-chapter assignments, this text provides both theory and practice for those coming to digital control engineering for the first time, whether as a student or practicing engineer. Extensive Use of computational tools: Matlab sections at end of each chapter show how to implement concepts from the chapter Frees the student from the drudgery of mundane calculations and allows him to consider more subtle aspects of control system analysis and design An engineering approach to digital controls: emphasis throughout the book is on design of control systems. Mathematics is used to help explain concepts, but throughout the text discussion is tied to design and implementation. For example coverage of analog controls in chapter 5 is not simply a review, but is used to show how analog control systems map to digital control systems Review of Background Material: contains review material to aid understanding of digital control analysis and design. Examples include discussion of discrete-time systems in time domain and frequency domain (reviewed from linear systems course) and root locus design in s-domain and z-domain (reviewed from feedback control course) Inclusion of Advanced Topics In addition to the basic topics required for a one semester senior/graduate class, the text includes some advanced material to make it suitable for an introductory graduate level class or for two quarters at the senior/graduate level. Examples of optional topics are state-space methods, which may receive brief coverage in a one semester course, and nonlinear discrete-time systems Minimal Mathematics Prerequisites The mathematics background required for understanding most of the book is based on what can be reasonably expected from the average electrical, chemical or mechanical engineering senior. This background includes three semesters of calculus, differential equations and basic linear algebra. Some texts on digital control require more

Although LMI has emerged as a powerful tool with applications across the major domains of systems and control, there has been a need for a textbook that provides an accessible introduction to LMIs in control systems analysis and design. Filling this need, LMIs in Control Systems: Analysis, Design and Applications focuses on the basic analysis and d

This Encyclopedia of Control Systems, Robotics, and Automation is a component of the global Encyclopedia of Life Support Systems EOLSS, which is an integrated compendium of twenty one Encyclopedias. This 22-volume set contains 240 chapters, each of size 5000-30000 words, with perspectives, applications and extensive illustrations. It is the only publication of its kind carrying state-of-the-art knowledge in the fields of Control Systems, Robotics, and Automation and is aimed, by virtue of the several applications, at the following five major target audiences: University and College Students, Educators, Professional Practitioners, Research Personnel and Policy Analysts, Managers, and Decision Makers and NGOs.

Designed to help learn how to use MATLAB and Simulink for the analysis and design of automatic control systems.

Includes: Digital signals and systems. Digital controllers for process control applications. Design of digital controllers. Control of time delay systems. State-space concepts. System identification. Introduction to discrete optimal control. Multivariable control. Adaptive control. Computer aided design for industrial control systems. Reliability and redundancy in microprocessor controllers. Software and hardware aspects of industrial controller implementations. Application of distributed digital control algorithms to power stations. An expert system for process control.

Introduction; Review of continuous control; Introductory digital control; Discrete systems analysis; Sampled-data systems; Discrete equivalents; Design using transform techniques; Design using state-space methods; Multivariable and optimal control; Quantization effects; Sample rate selection; System identification; Nonlinear control; Design of a disk drive servo: a case study; Appendix A: Examples; Appendix B: Tables; Appendix C; A few results from matrix analysis; Appendix D: Summary of facts from the theory of probability and stochastic processes; Appendix E: Matlab functions; Appendix F; Differences between Matlab v5 and v4; References; Index.

This work presents traditional methods and current techniques of incorporating the computer into closed-loop dynamic systems control, combining conventional transfer function design and state variable concepts. Digital Control Designer - an award-winning software program which permits the solution of highly complex problems - is available on the CR

This book presents comprehensive coverage of linear control systems along with an introduction to digital control systems. It is designed for undergraduate courses in control systems taught in departments of electrical engineering, electronics and instrumentation, electronics and communication, instrumentation and control, and computer science and engineering. The text discusses the important concepts of control systems, transfer functions and system components. It describes system stability, employing the Hurwitz–Routh stability criterion, root locus technique, Bode plot, and polar and Nyquist plots. In addition, this student-friendly book features in-depth coverage of controllers, compensators, state-space modelling and discrete time systems. KEY FEATURES •Includes a brief tutorial on MATLAB in an appendix to help students learn how to use it for the analysis and design of control systems. •Provides an abundance of worked-out examples and review questions culled from university examination papers. •Gives answers to selected chapter-end questions at the end of the book.

The Book Provides An Integrated Treatment Of Continuous-Time And Discrete-Time Systems For Two Courses At Undergraduate Level Or

One Course At Postgraduate Level. The Stress Is On The Interdisciplinary Nature Of The Subject And Examples Have Been Drawn From Various Engineering Disciplines To Illustrate The Basic System Concepts. A Strong Emphasis Is Laid On Modeling Of Practical Systems Involving Hardware; Control Components Of A Wide Variety Are Comprehensively Covered. Time And Frequency Domain Techniques Of Analysis And Design Of Control Systems Have Been Exhaustively Treated And Their Interrelationship Established. Adequate Breadth And Depth Is Made Available For A Second Course. The Coverage Includes Digital Control Systems: Analysis, Stability And Classical Design; State Variables For Both Continuous-Time And Discrete-Time Systems; Observers And Pole-Placement Design; Liapunov Stability; Optimal Control; And Recent Advances In Control Systems: Adaptive Control, Fuzzy Logic Control, Neural Network Control. Salient Features * State Variables Concept Introduced Early In Chapter 2 * Examples And Problems Around Obsolete Technology Updated. New Examples Added * Robotics Modeling And Control Included * Pid Tuning Procedure Well Explained And Illustrated * Robust Control Introduced In A Simple And Easily Understood Style * State Variable Formulation And Design Simplified And Generalizations Built On Examples * Digital Control; Both Classical And Modern Approaches, Covered In Depth * A Chapter On Adaptive, Fuzzy Logic And Neural Network Control, Amenable To Undergraduate Level Use, Included * An Appendix On Matlab With Examples From Time And Frequency Domain Analysis And Design, Included

Written to inspire and cultivate the ability to design and analyze feasible control algorithms for a wide range of engineering applications, this comprehensive text covers the theoretical and practical principles involved in the design and analysis of control systems. From the development of the mathematical models for dynamic systems, the author shows how they are used to obtain system response and facilitate control, then addresses advanced topics, such as digital control systems, adaptive and robust control, and nonlinear control systems.

"Illustrates the analysis, behavior, and design of linear control systems using classical, modern, and advanced control techniques. Covers recent methods in system identification and optimal, digital, adaptive, robust, and fuzzy control, as well as stability, controllability, observability, pole placement, state observers, input-output decoupling, and model matching."

This text's contemporary approach focuses on the concepts of linear control systems, rather than computational mechanics. Straightforward coverage includes an integrated treatment of both classical and modern control system methods. The text emphasizes design with discussions of problem formulation, design criteria, physical constraints, several design methods, and implementation of compensators. Discussions of topics not found in other texts--such as pole placement, model matching and robust tracking--add to the text's cutting-edge presentation. Students will appreciate the applications and discussions of practical aspects, including the leading problem in developing block diagrams, noise, disturbances, and plant perturbations. State feedback and state estimators are designed using state variable equations and transfer functions, offering a comparison of the two approaches. The incorporation of MATLAB throughout the text helps students to avoid time-consuming computation and concentrate on control system design and analysis.

Thoroughly classroom-tested and proven to be a valuable self-study companion, Linear Control System Analysis and Design: Sixth Edition provides an intensive overview of modern control theory and conventional control system design using in-depth explanations, diagrams, calculations, and tables. Keeping mathematics to a minimum, the book is designed with the undergraduate in mind, first building a foundation, then bridging the gap between control theory and its real-world application. Computer-aided design accuracy checks (CADAC) are used throughout the text to enhance computer literacy. Each CADAC uses fundamental concepts to ensure the viability of a computer solution. Completely updated and packed with student-friendly features, the sixth edition presents a range of updated examples using MATLAB®, as well as an appendix listing MATLAB functions for optimizing control system analysis and design. Over 75 percent of the problems presented in the previous edition have been revised or replaced.

An introduction to analysis techniques used in the design of linear feedback control systems with emphasis on both classical and matrix methods. This text presents all design methods in a building-block sequence, including a thorough analysis of first- and second-order systems as well as general state space systems.

A Complete One-Stop Resource While digital color is now the technology of choice for printers, the knowledge required to address the quality and productivity issues of these devices is scattered across several technologies, as is its supporting literature. Bringing together information from diverse fields, Control of Color Imaging Systems: Analysis and Design is the first book to provide comprehensive coverage of the fundamentals and algorithms of the numerous disciplines associated with digital color printing in a single resource. The authors review the history of digital printing systems, explore its current status, and explain fundamental concepts, including: digital image formation, sampling, quantization, image coding, spot color calibration, and one- and multi-dimensional tone control of color management systems — including process physics and controls. A Complete Self-Tutorial With Over 150 Design Examples and 120 Exercise Problems Based on the authors' three decades of hands-on technical and teaching experience, the text provides engineers and technicians with an end-to-end understanding of the color printing process, and helps them build a foundation drawn from the diverse disciplines needed to manage and control digital production printers. The control theory and methods presented in this book are state-of-the art for color printing systems; however, coverage of theoretical concepts and mathematics are kept to the basics, as the book is designed to teach hands on skills that will allow practitioners to gain an immediate understanding of quality and productivity concerns. The understanding provided will help practitioners build the technical skills needed to help pioneer the next generation of ideas, algorithms, and methods that will further expand the frontier of this rapidly evolving technology.

Advanced Control Engineering provides a complete course in control engineering for undergraduates of all technical disciplines. Included are real-life case studies, numerous problems, and accompanying MatLab programs.

Provides complete coverage of both the Lyapunov and Input-Output stability theories, in a readable, concise manner. * Supplies an introduction to the popular backstepping approach to nonlinear control design * Gives a thorough discussion of the concept of input-to-state stability * Includes a discussion of the fundamentals of feedback linearization and related results. * Details complete coverage of the fundamentals of dissipative system's theory and its application in the so-called L2gain control problem, for the first time in an introductory level textbook. * Contains a thorough discussion of nonlinear observers, a very important problem, not commonly encountered in textbooks at this level. * An Instructor's Manual presenting detailed solutions to all the problems in the book is available from the Wiley editorial department.

“Reliability and Risk Issues in Large Scale Safety-critical Digital Control Systems” provides a comprehensive coverage of reliability issues and their corresponding countermeasures in the field of large-scale digital control systems, from the hardware and software in digital systems to the human operators who supervise the overall process of large-scale systems. Unlike other books which examine theories and issues in individual fields, this book reviews important problems and countermeasures across the fields of software reliability, software verification and validation, digital systems, human factors engineering and human reliability analysis. Divided into four sections dealing with software reliability, digital system reliability, human reliability and human operators in large-scale digital systems, the book offers insights from professional researchers in each specialized field in a diverse yet unified approach.

A text for a first course in discrete control systems or a first course in digital filters, at senior or first-year graduate level. Covers discrete-time systems and the z-transform, stability analysis techniques, digital controller design, and digital filter structures. The appendices list design eq This book is intended to be used as a text for an introductory control systems course offered in the upper terms. It could also be used by students as supplementary material for self study and as an additional source of information. Problem solutions are provided for all the problems in the book in order to provide the student with an extensive source of worked examples. The book covers control systems analysis and design of single input single output (SISO) systems for both continuous time and discrete time. MATLAB and Scilab design and analysis software are also used.

The extraordinary development of digital computers (microprocessors, microcontrollers) and their extensive use in control systems in all fields of applications has brought about important changes in the design of control systems. Their performance and their low cost make them suitable for use in control systems of various kinds which demand far better capabilities and performances than those provided by analog controllers. However, in order really to take advantage of the capabilities of microprocessors, it is not enough to reproduce the behavior of analog (PID) controllers. One needs to implement specific and high-performance model based control techniques developed for computer-controlled systems (techniques that have been extensively tested in practice). In this context identification of a plant dynamic model from data is a fundamental step in the design of the control system. The book takes into account the fact that the association of books with software and on-line material is radically changing the teaching methods of the control discipline. Despite its interactive character, computer-aided control design software requires the understanding of a number of concepts in order to be used efficiently. The use of software for illustrating the various concepts and algorithms helps understanding and rapidly gives a feeling of the various phenomena.

Signal processing in digital control - Models of digital control devices and systems - Design of digital control algorithms - Control system analysis using state variable methods - Variable analysis of digital control systems - Pole-placement design and state observers - Lyapunov stability analysis - Linear quadratic optimal control - Nonlinear control systems - Neural networks for control - Fuzzy control.

Praise for Previous Volumes "This book will be a useful reference to control engineers and researchers. The papers contained cover well the recent advances in the field of modern control theory." -IEEE GROUP CORRESPONDENCE "This book will help all those researchers who valiantly try to keep abreast of what is new in the theory and practice of optimal control." -CONTROL

Cloud Control Systems: Analysis, Design and Estimation introduces readers to the basic definitions and various new developments in the growing field of cloud control systems (CCS). The book begins with an overview of cloud control systems (CCS) fundamentals, which will help beginners to better understand the depth and scope of the field. It then discusses current techniques and developments in CCS, including event-triggered cloud control, predictive cloud control, fault-tolerant and diagnosis cloud control, cloud estimation methods, and secure control/estimation under cyberattacks. This book benefits all researchers including professors, postgraduate students and engineers who are interested in modern control theory, robust control, multi-agents control. Offers insights into the innovative application of cloud computing principles to control and automation systems Provides an overview of cloud control systems (CCS) fundamentals and introduces current techniques and developments in CCS Investigates distributed denial of service attacks, false data injection attacks, resilient design under cyberattacks, and safety assurance under stealthy cyberattacks

A guide to common control principles and how they are used to characterize a variety of physiological mechanisms The second edition of Physiological Control Systems offers an updated and comprehensive resource that reviews the fundamental concepts of classical control theory and how engineering methodology can be applied to obtain a quantitative understanding of physiological systems. The revised text also contains more advanced topics that feature applications to physiology of nonlinear dynamics, parameter estimation methods, and adaptive estimation and control. The author—a noted expert in the field—includes a wealth of worked examples that illustrate key concepts and methodology and offers in-depth analyses of selected physiological control models that highlight the topics presented. The author discusses the most noteworthy developments in system identification, optimal control, and nonlinear dynamical analysis and targets recent bioengineering advances. Designed to be a practical resource, the text includes guided experiments with simulation models (using Simulink/Matlab). Physiological Control Systems focuses on common control principles that can be used to characterize a broad variety of physiological mechanisms. This revised resource: Offers new sections that explore identification of nonlinear and time-varying systems, and provide the background for understanding the link between continuous-time and discrete-time dynamic models Presents helpful, hands-on experimentation with computer simulation models Contains fully updated problems and exercises at the end of each chapter Written for biomedical engineering students and biomedical scientists, Physiological Control Systems, offers an updated edition of this key resource for understanding classical control theory and its application to physiological systems. It also contains contemporary topics and methodologies that shape bioengineering research today.

The objective of this book is to provide a collection of solved problems on control systems, with an emphasis on practical problems. System functionality is described, the modeling process is explained, the problem solution is introduced, and the derived results are discussed. Each chapter ends with a discussion on applying MATLAB®, LabVIEW, and/or Comprehensive Control to the previously introduced concepts. The aim of the book is to help an average reader understand the concepts of control systems through problems and applications. The solutions are based directly on math formulas given in extensive tables throughout the text.

Digital Control Applications Illustrated with MATLAB covers the modeling, analysis, and design of linear discrete control systems. Illustrating all topics using the micro-computer implementation of digital controllers aided by MATLAB, Simulink, and FEEDBACK

This book adopts a systematic view of the control systems in cyber-physical systems including the security control of the optimal control system, security control of the non-cooperative game system, quantify the impact of the Denial-of-Service attacks on the optimal control system, and the adaptive security control of the networked control systems. Because the cyber-physical system is a hybrid system, it adopts cross layer approach to handle the security control of the CPS. It presents a number of attack models according to the attack scenario and defense facilities, and a number of cross-layer

co-design methodologies to secure the control of CPS.

The intent of this book is to emphasize the basics of control system. These basics include transfer function, block diagram, signal flow graph, and the matrix approach in solving simultaneous differential equations. Additionally, they also include Bode plot, realization diagram, and stability analysis. The book also shows digital control system as an extension of analog control system. To illustrate these basics, the author used extensive figures and tables. Each figure consists of sketches and mathematical equations shown on its text. Such an approach minimizes backward referencing from a figure to its text and vice versa. After a careful study of the book, an engineer should be able to design, analyze, or test a control system.

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